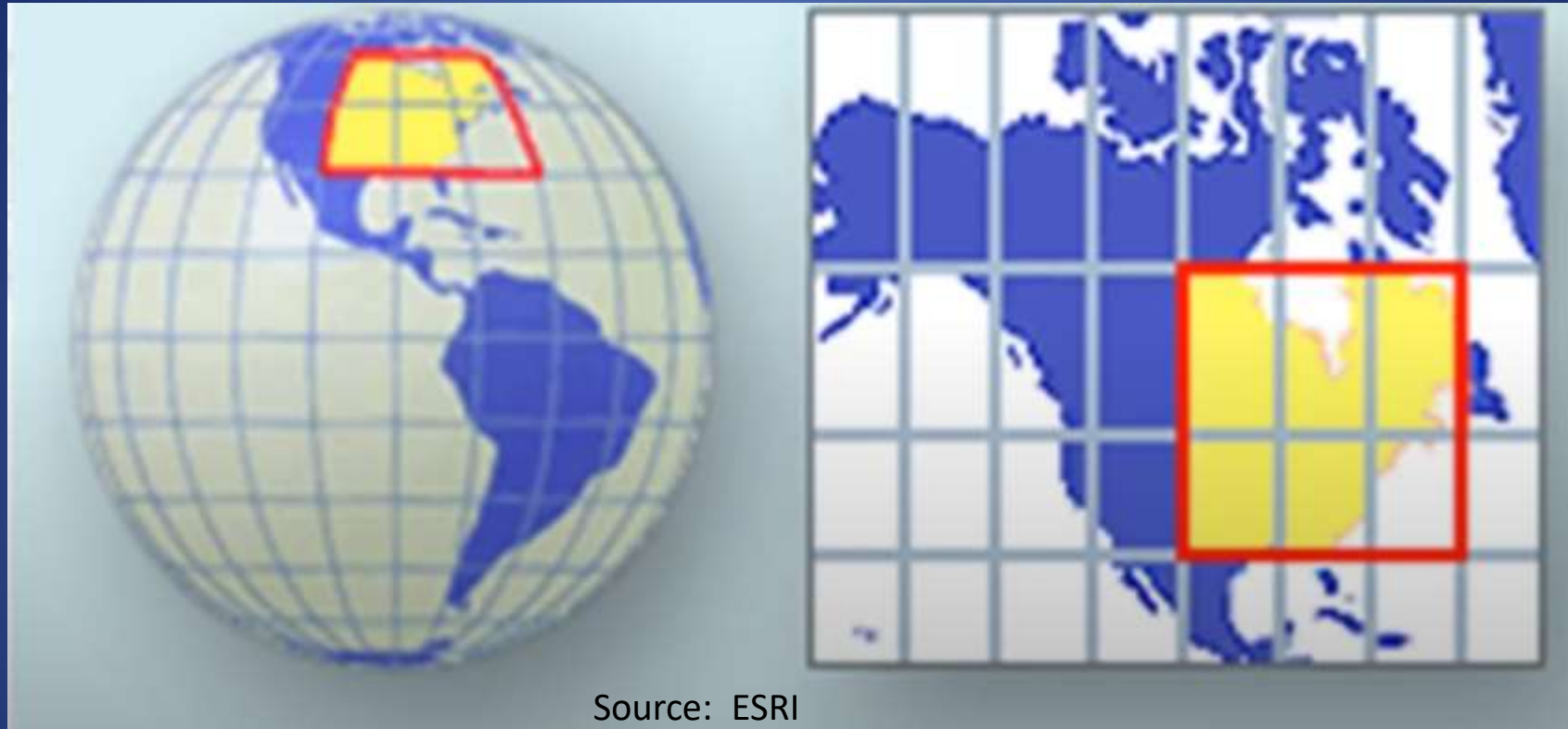


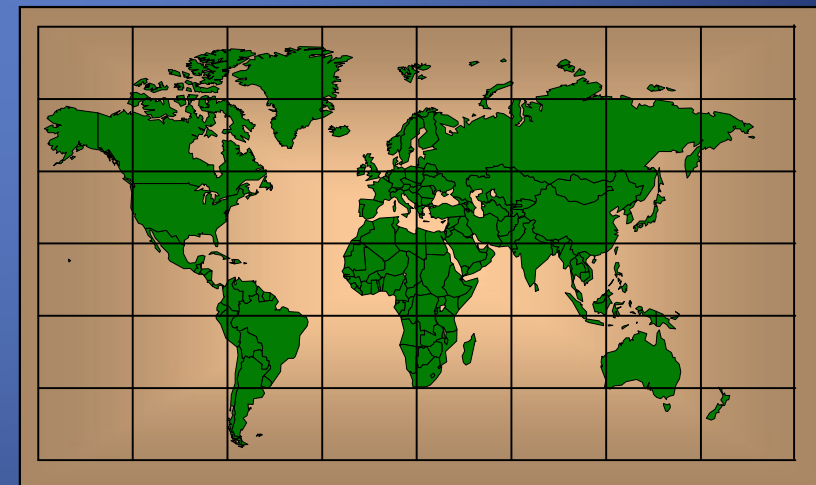
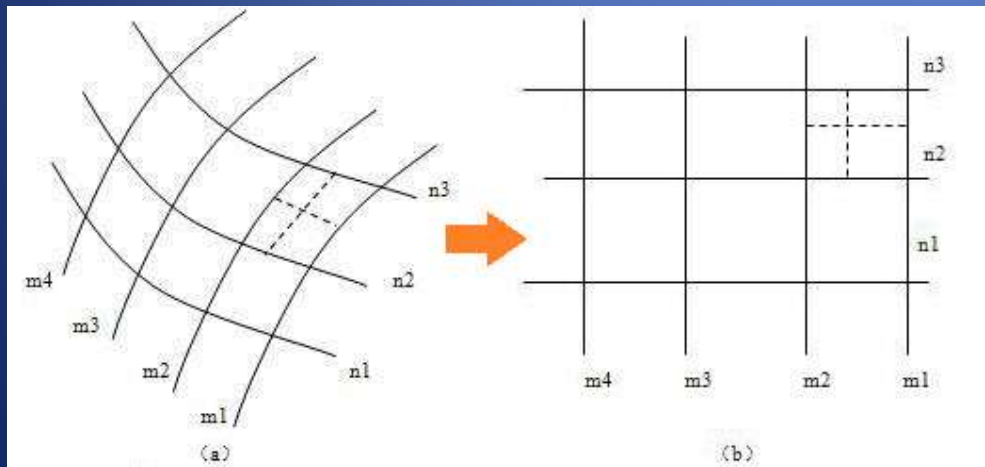
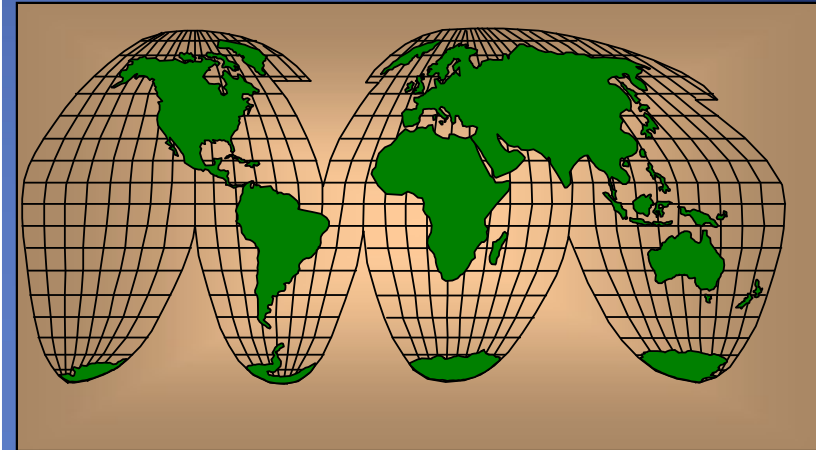
MAP PROJECTION



- Series of theories and methods by which the curved surface of the earth is portrayed on a flat surface
- This requires a systematic mathematical transformation of the earth's graticule of lines of latitude and longitude onto a plane

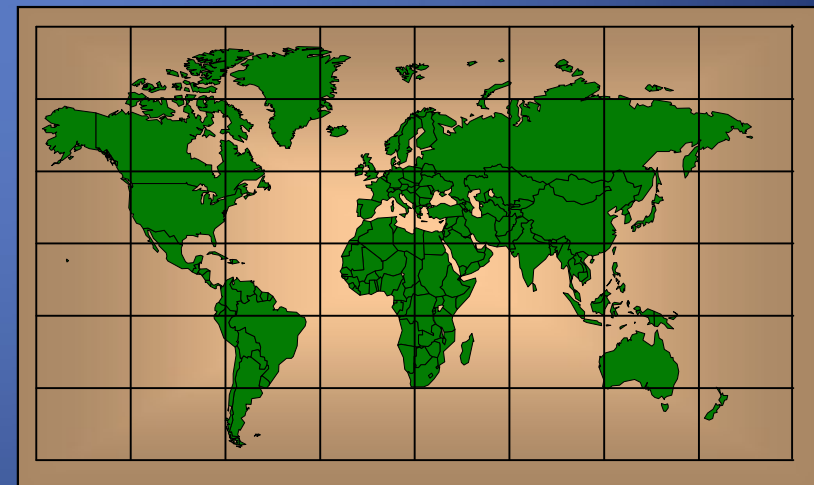
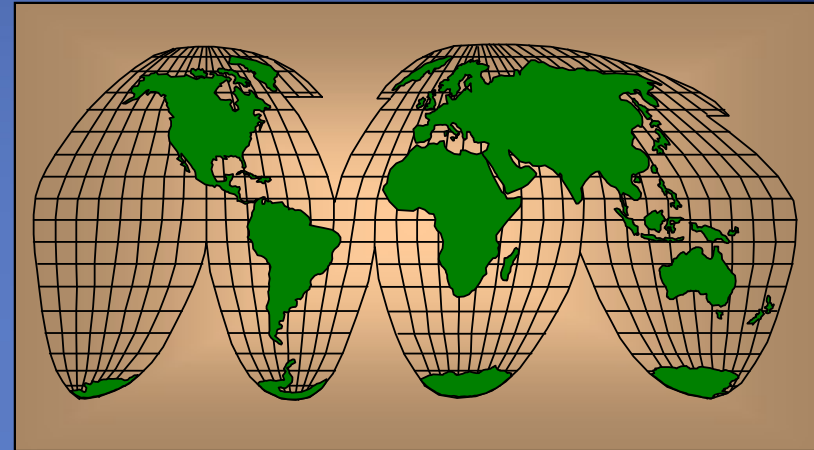
PROJECTED COORDINATE SYSTEM

- The **coordinate system** is used to determine the position of any point on the earth. The map uses different projection methods, and its corresponding coordinate system is also different.



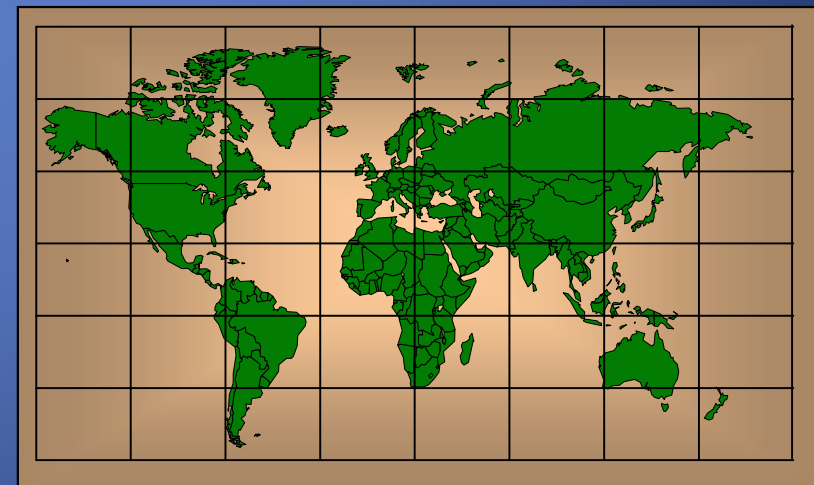
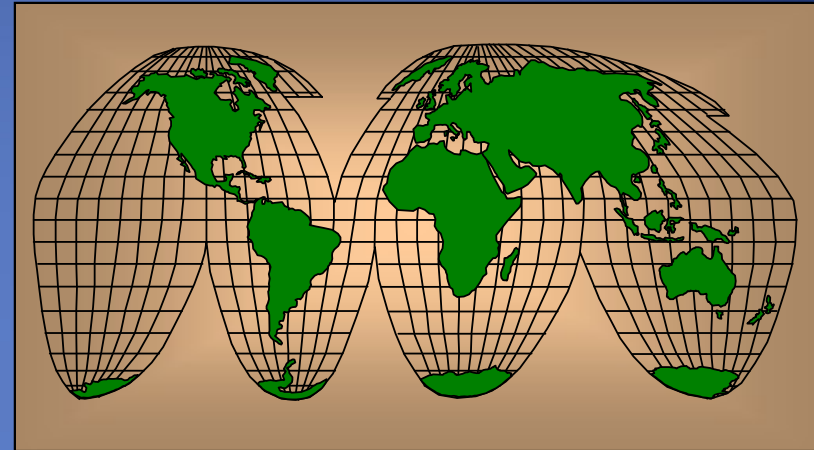
PROJECTED COORDINATE SYSTEM

- Also c/a **Plane Coordinate System**
- Based on a map projection
- Relates the coordinates of points on earth's curved surface with the coordinates of the same points on a plane or flat surface
- Key consideration is accuracy in a feature's location and its position
- Defined not only by the parameters of map projection but also the parameters of the GCS it is derived from



PROJECTED COORDINATE SYSTEM

- Also c/a **Plane Coordinate System**
- The graticule represents positions on 3D surface of the Earth that have been projected or transformed onto the 2D surface of the map
- The **rectangular coordinate grid is superimposed on the graticule** so that positions of mapped features can be georeferenced by means of linear measurements rather than by angular measurements

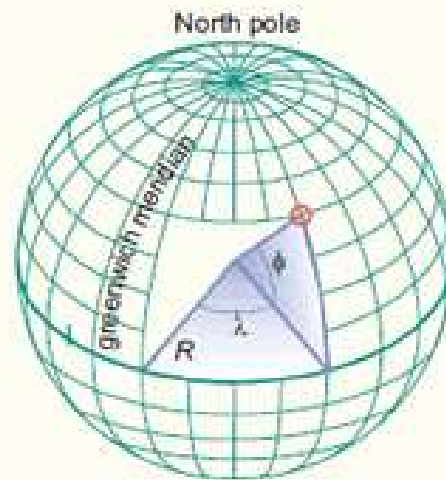
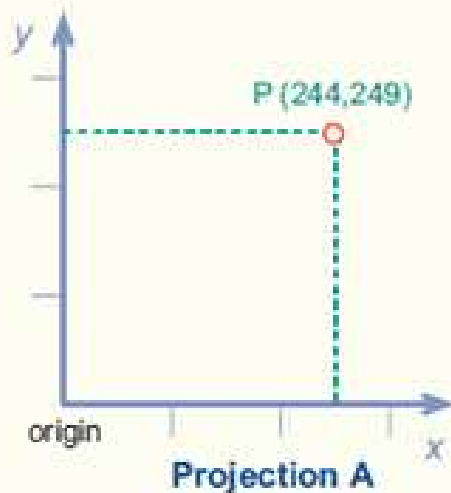


GCS, Projection and PCS

**GCS tells me where
on the earth the
data should draw**

*Inverse mapping
equations*

Cartesian reference
coordinate system I



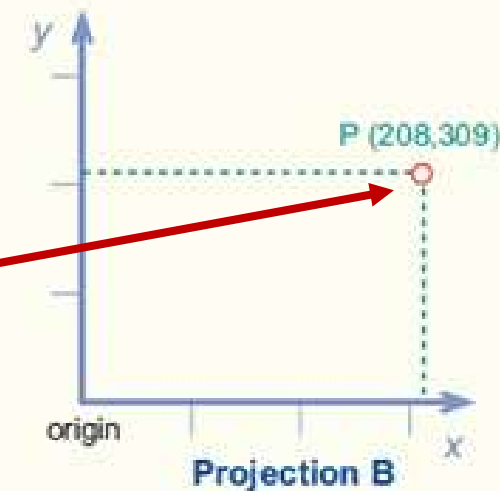
<https://kartoweb.itc.nl/>

*Forward mapping
equations*

Cartesian reference
coordinate system II

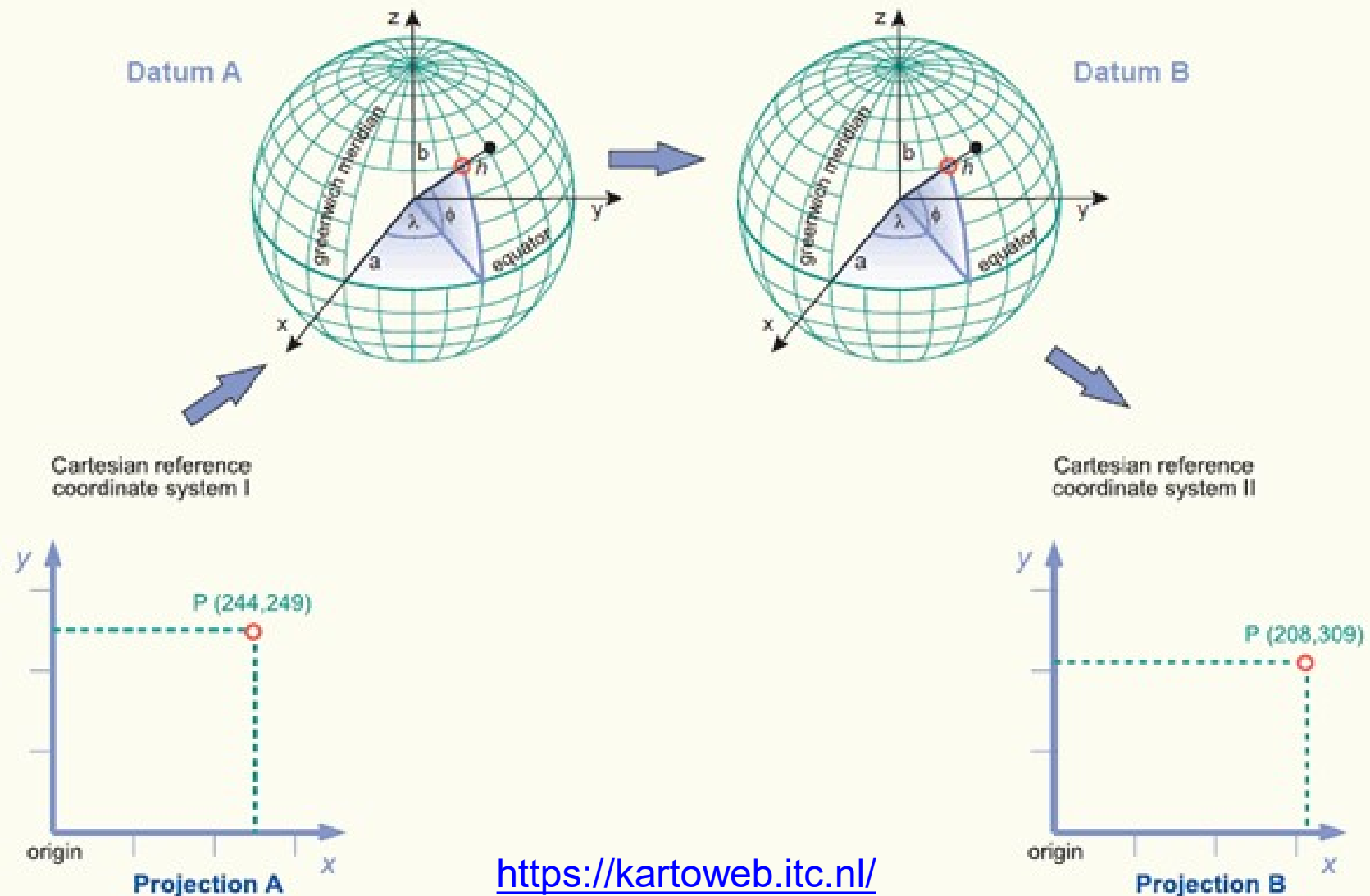
**Projection tells me
how to draw the
earth on a flat
surface**

**CS tells me where
does the data draw
on the flat surface**



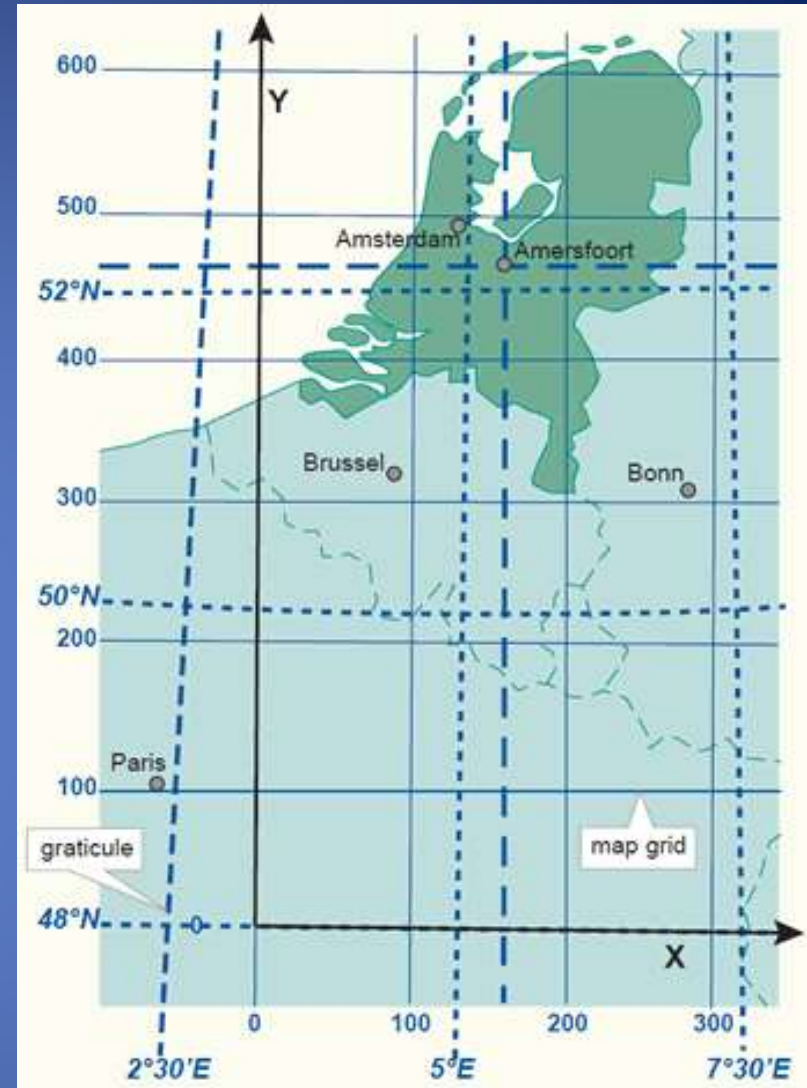
- Coordinate systems are constructed based on map projections, they are not map projections themselves

Coordinate Transformation



Map projections and coordinate systems serve two different purposes in geo-referencing

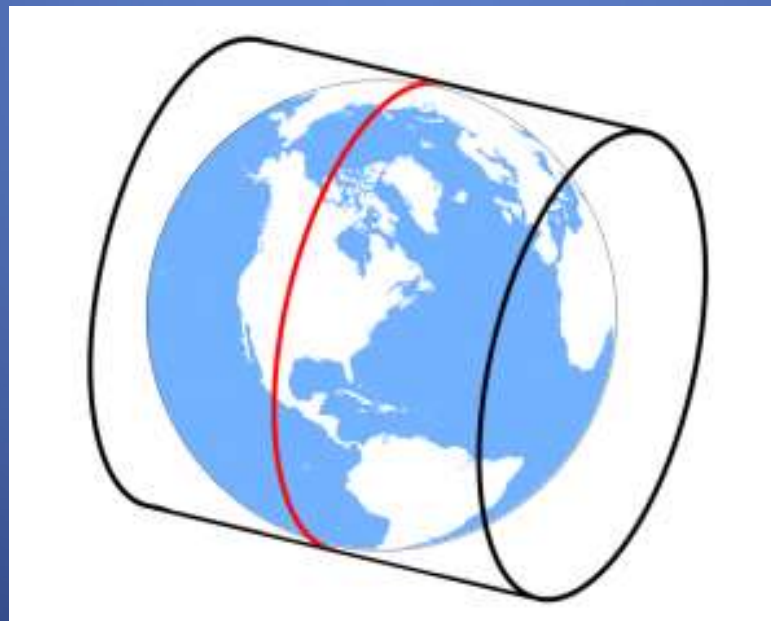
- The function of map projections is to define how positions on the Earth's curved surface are transformed onto a flat map surface
- Coordinate system is then superimposed on the surface to provide the referencing framework by which positions are measured and computed



<https://kartoweb.itc.nl/geometrics/Coordinate%20systems/coordsys.html>

The UNIVERSAL TRANSVERSE MERCATOR CS

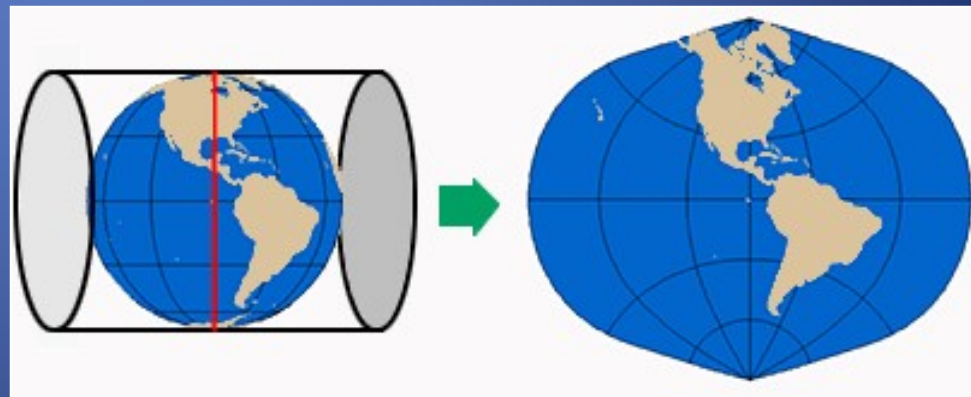
- UTM is based on the Transverse Mercator projection.
- **Transverse Mercator:** Invented by Johann Heinrich Lambert in 1772. Modified Mercator projection
- Transverse aspect - the axis of the cylinder is rotated 90° , so the tangent line is longitudinal, rather than equatorial



TRANSVERSE MERCATOR PROJECTION

- In this case, only the central longitudinal meridian and the equator are straight lines. Distances are true along the central meridian
- It is a conformal projection
- All distances, directions, shapes and areas are reasonably close to the Central Meridian
- Shapes and angles within any small area are essentially true
- However, meridians and parallels are no longer straight lines as in case of the regular Mercator Projection

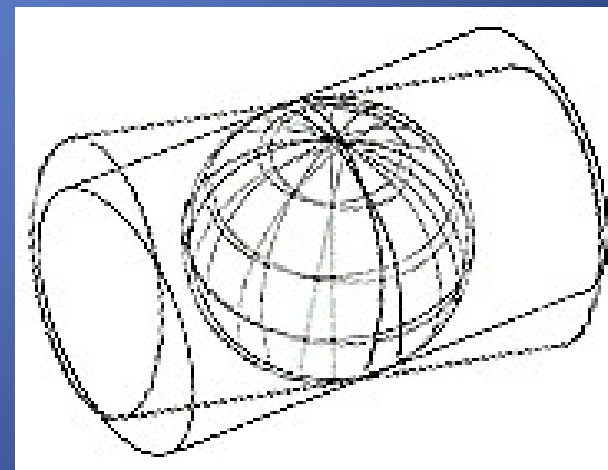
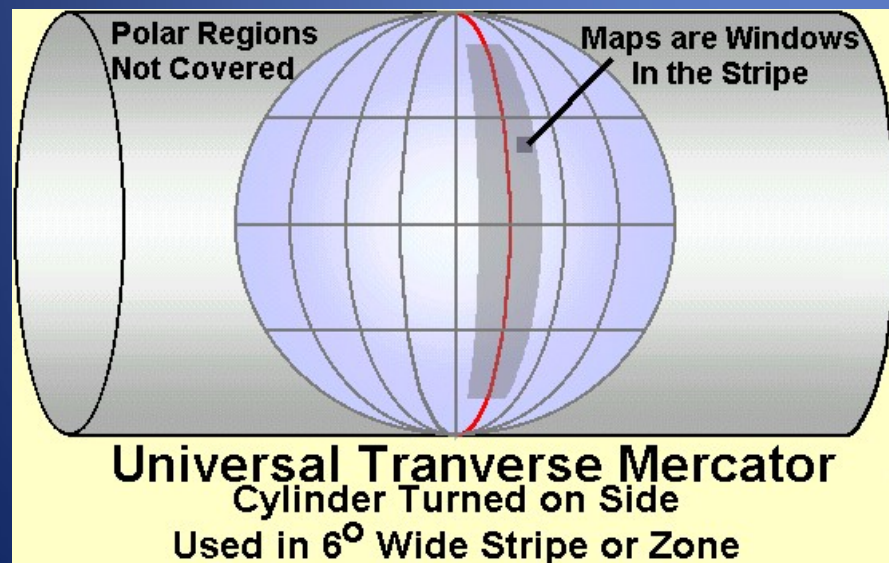
All other lines are represented by complex curves: that is they can't be represented by single section of a circle



Source: ESRI

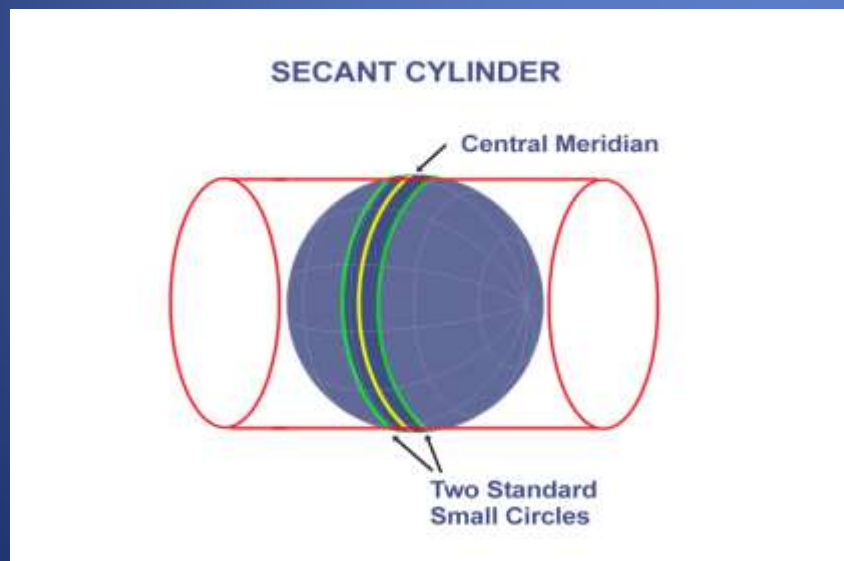
UNIVERSAL TRANSVERSE MERCATOR PROJECTION

- TM projection modified to minimize the distortions so that it can be used for georeferencing (by US Army post World War II)
- The projection is applied repeatedly by using multiple cylinders that touch the globe at 6 degree intervals, resulting in 60 projection zones each of 6 degree longitude. Each UTM zone is projected separately .
- To avoid extreme distortions that occur in polar areas, the projection zones are limited to 84 deg North to 80 deg South



UNIVERSAL TRANSVERSE MERCATOR PROJECTION

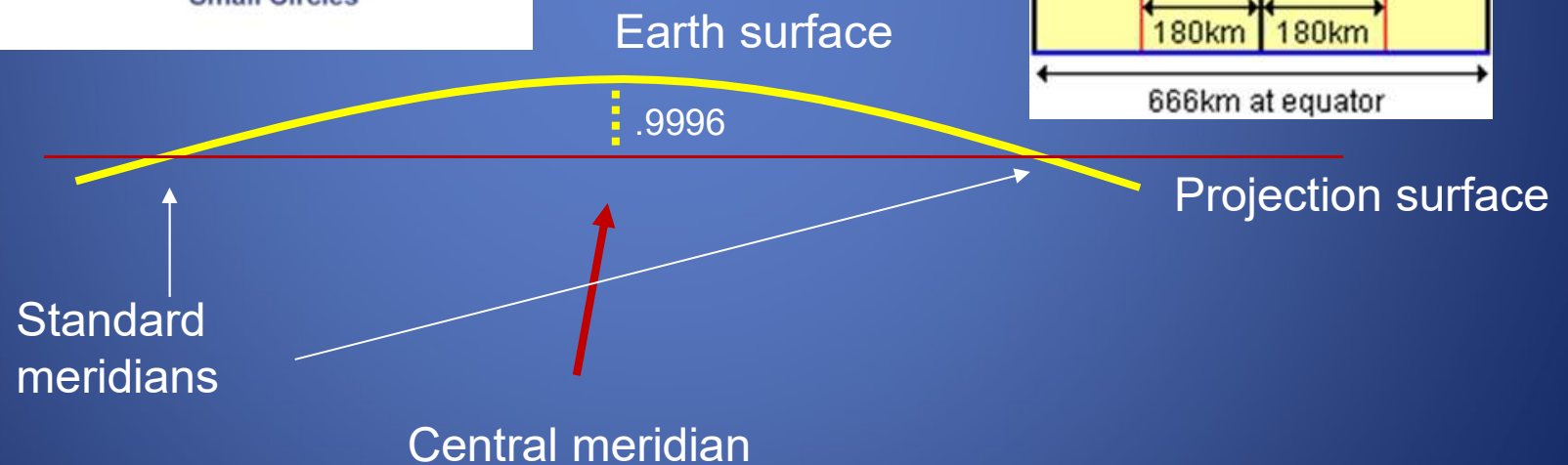
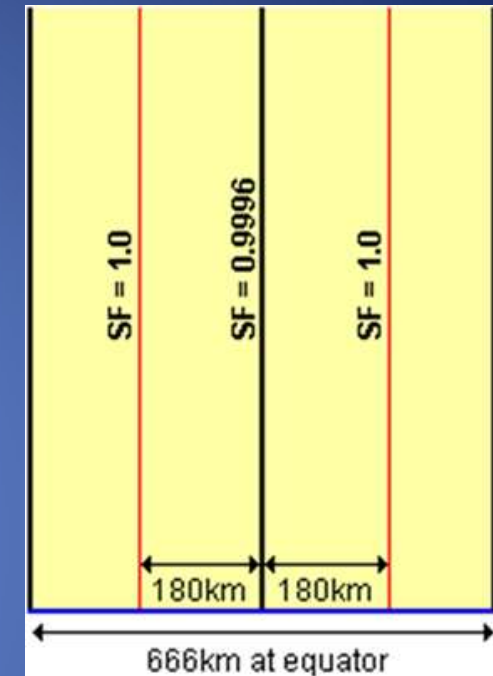
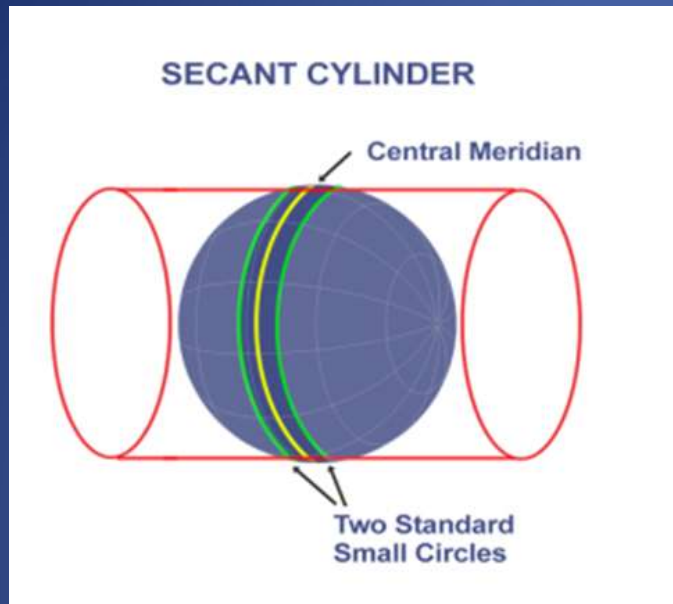
- To improve the overall accuracy of measurements within a projection zone, the cylinder is made to intersect the globe at two standard meridians that are 180 km east and west of the central meridian (i.e. a secant cylinder)
- This gives true scale along two standard meridians of longitude instead of one along the central meridian



Each zone uses a custom
Transverse Mercator projection
with its own central meridian

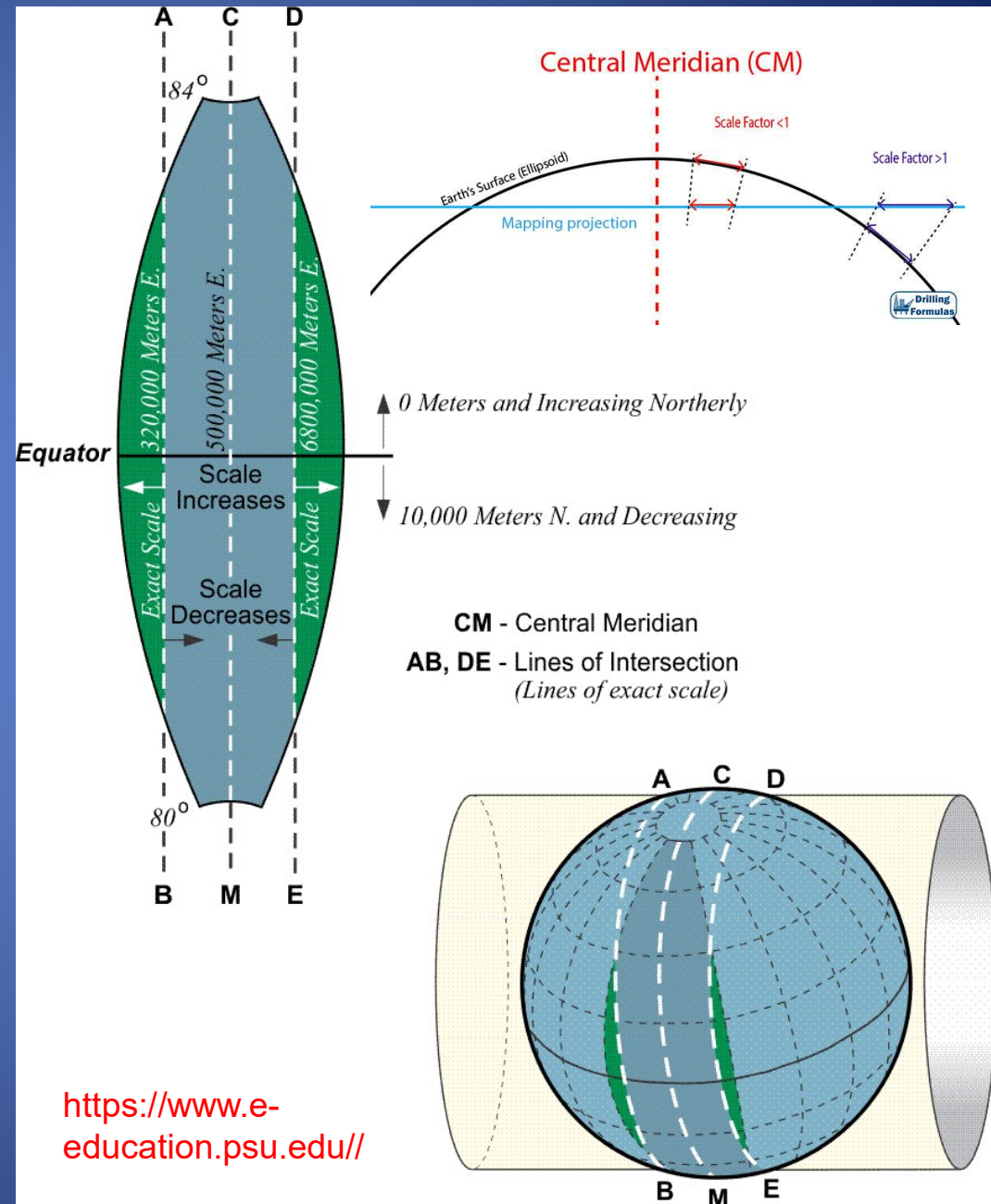
There is a false origin (zero
point) in each zone

- Scale factors are .9996 in the middle and 1 at the secants



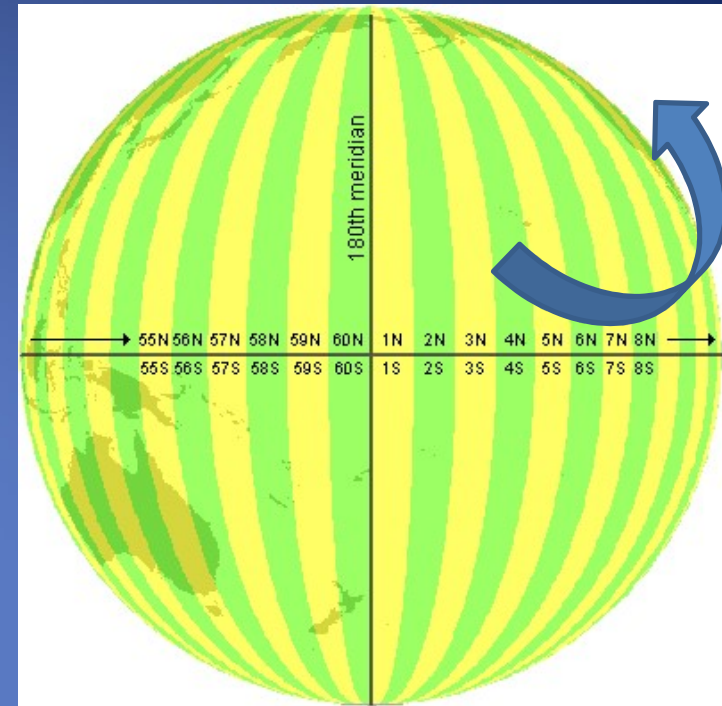
UNIVERSAL TRANSVERSE MERCATOR PROJECTION

- To compensate for scale distortion that is introduced along the central meridian, a scale factor slightly less than unity (@ 0.9996) is applied to all distance measurements.
- Similarly, a scale factor slightly greater than unity (@ 1.0004) is also applied to compensate for distortions in all distance measurements near the zone boundaries



UTM COORDINATE SYSTEM

- ✚ The UTM coordinate system is formed by superimposing a regular square grid on each UTM projection zone of 6 deg longitude width
- ✚ The grid is aligned so that the vertical lines are parallel to the central meridian
- ✚ There are 60 longitudinal projection zones – each 6 deg wide. They are numbered 1 to 60 starting at 180° W - International date line also c/a **the antemeridian** – proceeding towards east

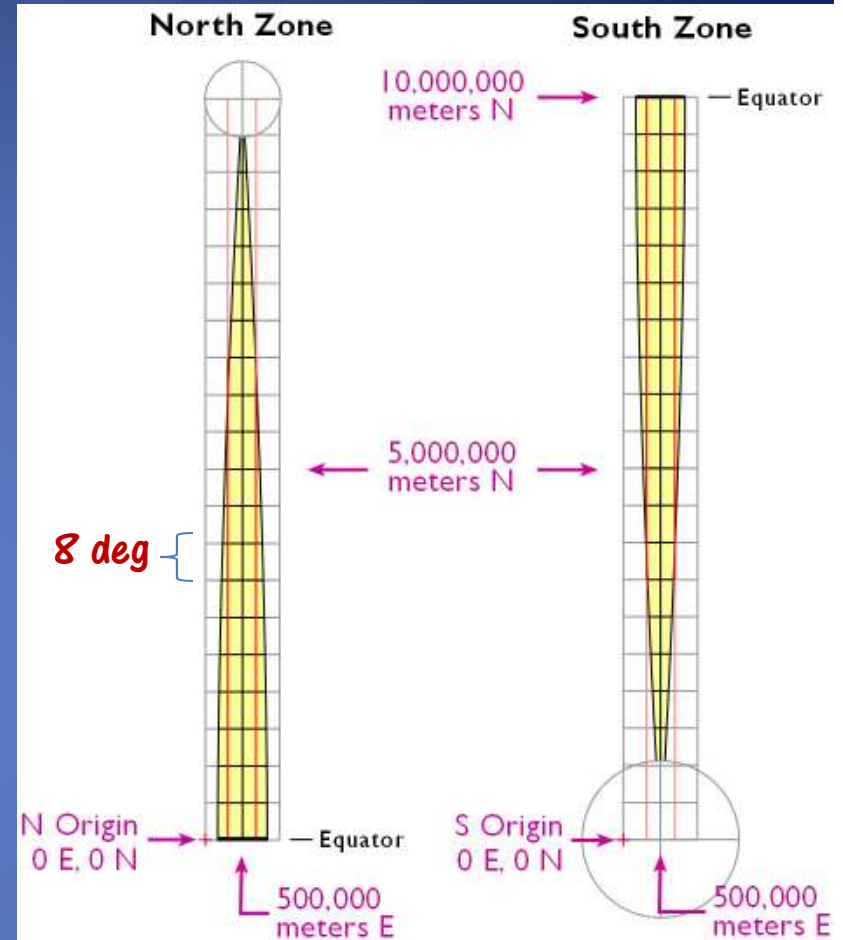


The longitudinal extension of ZONE 1 will be???

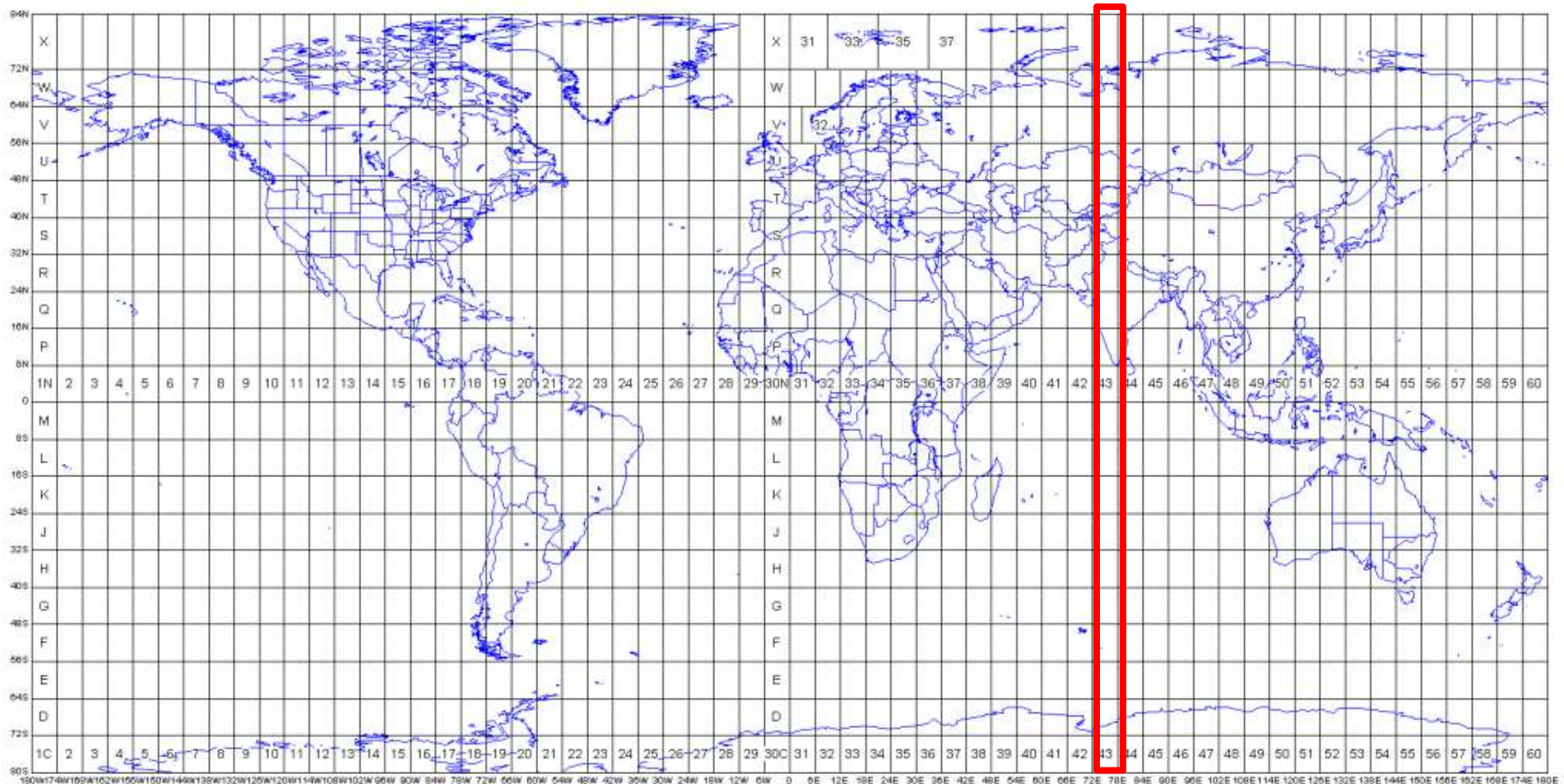
Central meridian of Zone 1 will be?

UTM COORDINATE SYSTEM

- Each UTM Zone (84° N to 80° S) is divided into horizontal bands spanning 8° of latitude
- There are 20 latitudinal zones
- They are identified by letters south to north beginning at 80° S from 'C' and ending at 84° N at 'X', Omitting letter 'I' and 'O' to avoid confusion with numbers 1 and 0.
- Only zone 'X' is 12 degrees N-S
- Areas are referenced by longitudinal zone number, followed by the latitudinal zone letter.

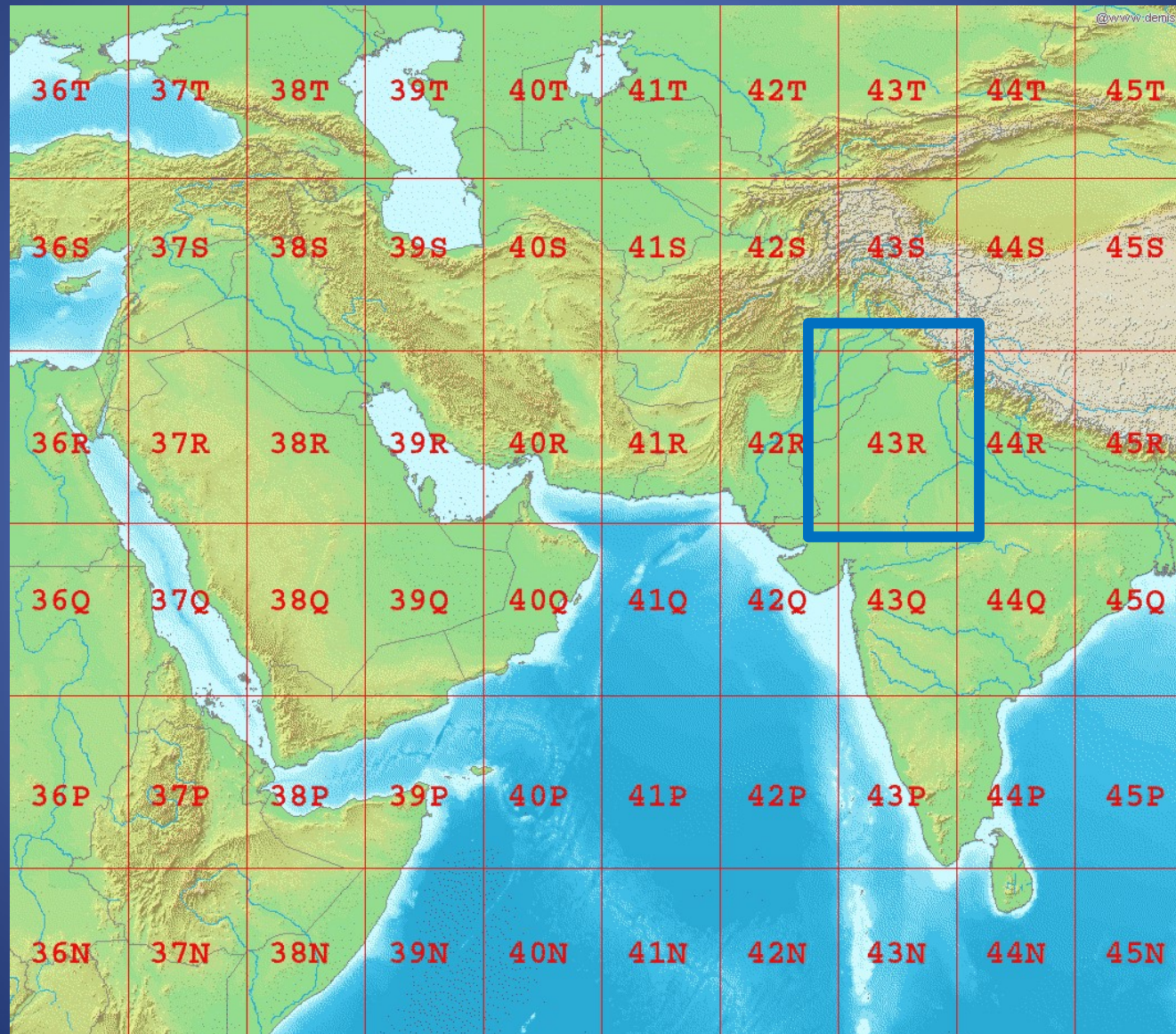


- UTM divisions of the earth between 84°N and 80°S (60 zones, each of which covers 6 degrees of longitude)
- Zone 1 begins at 180 ° W longitude.



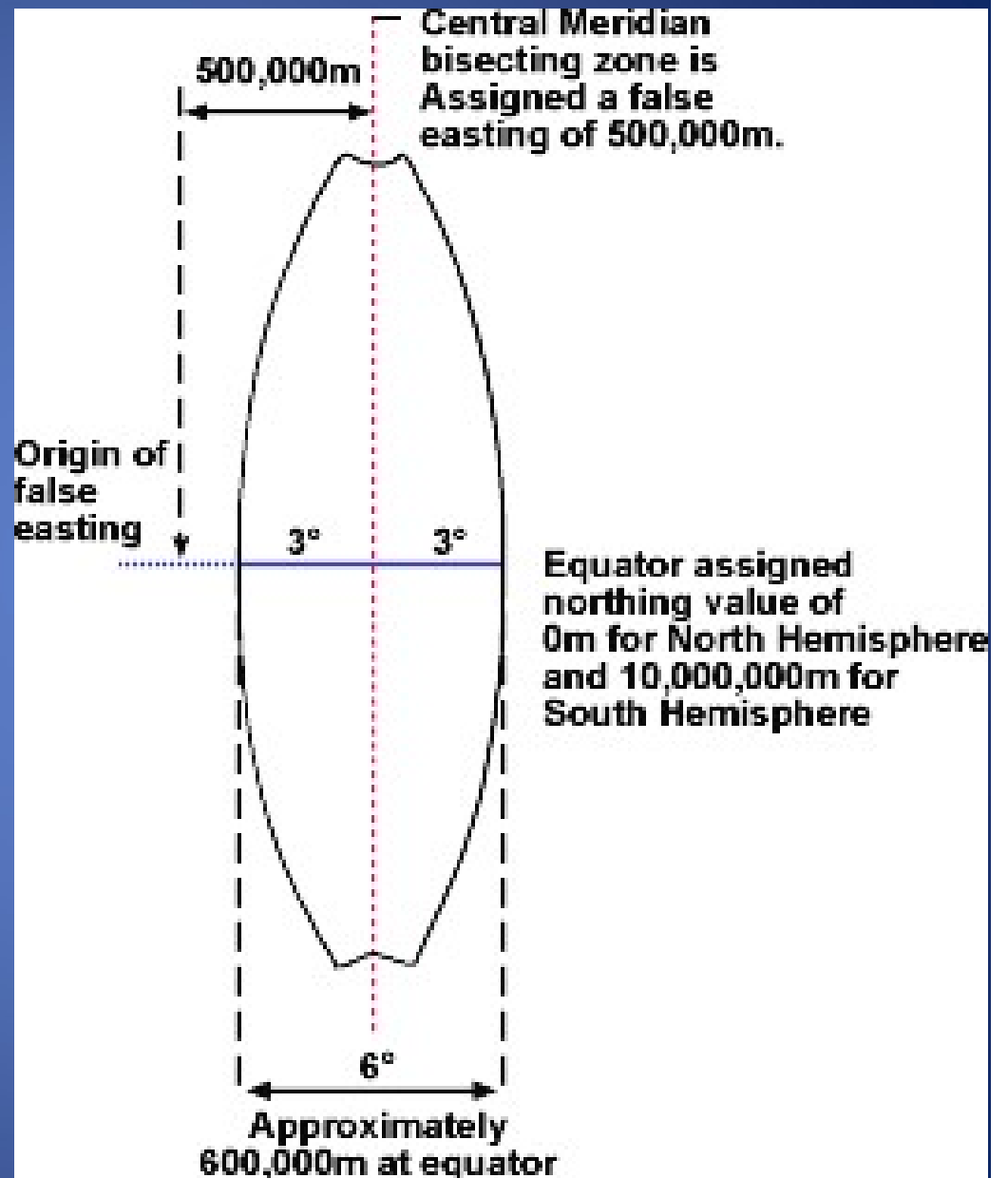
World UTM zones

UTM GRID – INDIA



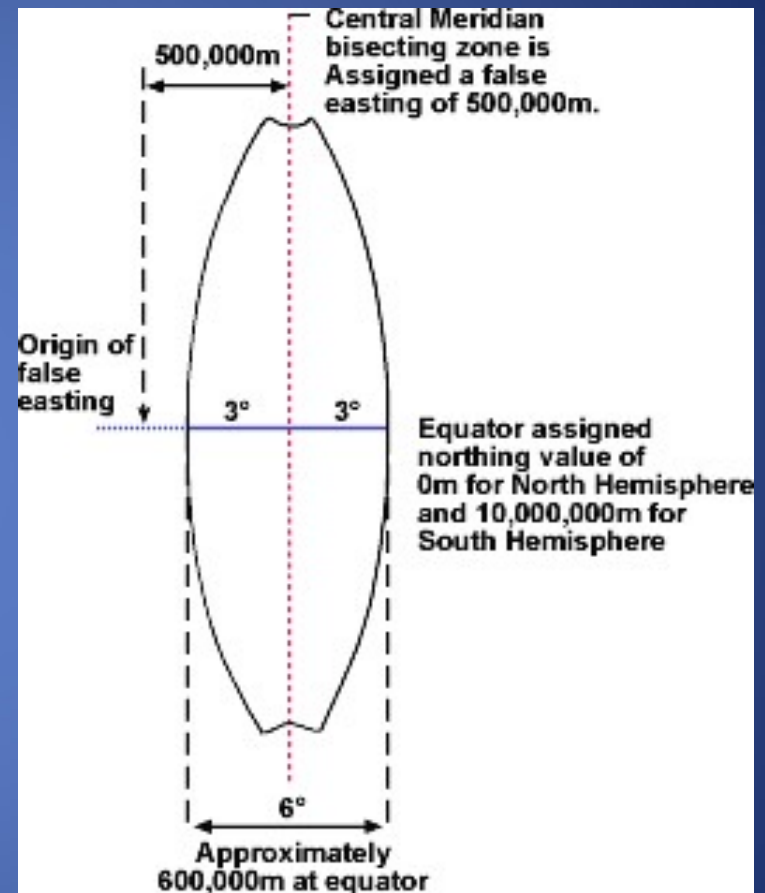
UTM COORDINATES

- UTM coordinates are expressed as a distance in meters to the east, referred to as 'easting' and a distance in meters to the north, referred to as 'northing'
- Eastings are referenced to the central meridian, which is assigned a value of 500,000. This gives the zone a false origin that is 500,000 m west of the central meridian. This eliminates the use of negative values for western half of the zone



UTM COORDINATES

- 🚧 **Northings** are referenced to the Equator.
For fixing position in the northern hemisphere, the Equator is assigned a northing value of **0 (zero) m N**.
- 🚧 **To avoid negative numbers for locations south of Equator, in southern hemisphere position fixing is done with equator assigned a value of 10,000,000 m S.**
- 🚧 **Thus for the northings in the southern hemisphere, the origin is defined as a point 10000000 meters south of equator**



Locating a point in UTM Coordinate System

- ✚ The coordinates thus derived define a location within a UTM projection zone either North or South of Equator.
- ✚ But since the same coordinate system is repeated for each zone and hemisphere, it is necessary to **additionally state the UTM longitudinal zone** and either **the hemisphere or the latitudinal zone** to define the location uniquely world wide.
- ✚ Thus UTM Coordinate definition shall comprise (1) **Easting Coordinate value** (2) Northing coordinate value (3) **Zone Number** and (4) Hemisphere (N or S of Equator)

Coordinate Information of Udaipur

| | |
|-------------------------------|-----------------------------|
| Udaipur Latitude: | 24.58 |
| Udaipur Longitude: | 73.68 |
| Latitude DMS: | 24°34'48"N |
| Longitude DMS: | 73°40'48"E |
| UTM Easting: | 366,342.17 |
| UTM Northing: | 2,719,083.56 |
| UTM Zone: | 43R |
| Position from Earth's Center: | ENE |
| Elevation: | 598.8 Meters (1964.55 Feet) |

REMEMBER!!!!

- ❑ *Coordinates on same projection may be referenced on different DATUMS .*

Such coordinates will have different coordinate values.

- ❑ *Coordinate data may be unprojected but CANNOT be without a datum.*
- ❑ *Change of projection may result in change of Datum.*
- ❑ *It is possible to convert data from one Datum to another without projecting it.*

SUMMARY CONCEPTS

- ✓ Two basic locational systems: **geometric** or Cartesian (x, y, z) and **geographic** or gravitational (f, l, z)
- ✓ Mean sea level surface or geoid is approximated by an ellipsoid to define a horizontal earth **datum** which gives (f, l) and a vertical datum which gives distance above the geoid (z)

SUMMARY CONCEPTS (CONT.)

- To prepare a map, the earth is first reduced to a **globe** and then **projected** onto a flat surface
- Three basic types of map projections:
 - conic
 - cylindrical
 - Planar/azimuthal
- A particular projection is defined by a **datum**, a projection **type** and a set of projection **parameters**

SUMMARY CONCEPTS (CONT.)

- ✓ **Standard coordinate systems** use particular projections over zones of the earth's surface
- ✓ Types of standard coordinate systems:
 - ✓ **UTM**
 - ✓ **State Plane**
 - ✓ **Others too numerous to mention**
- ✓ Do not confuse the coordinate system of a set of datum for its projection
 - ✓ Example: A shapefile that uses the Texas State Plane Coordinate System is in the Lambert Conformal Conic Projection

WHAT DOES ALL THIS MEAN???

- Careful attention must be paid to the projection, datum and coordinate system for every piece of GIS data used.
- Failure to use data from the same system OR change the data (re-project) it to the desired system will result in overlay errors
 - Can range some small to SIGNIFICANT
 - Real danger is when the errors are small (possibly unnoticed)
- Shapefiles, images, grids all have this data inherent in their very creation.
 - Usually included in a system of files known as “metadata” or xxxxxx.PRJ file.